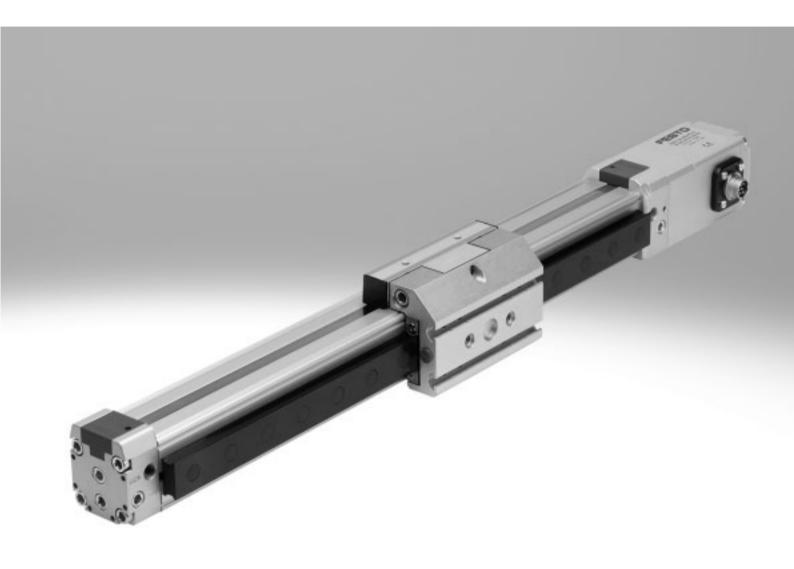


Linear drives DGPI/DGPIL, with integrated displacement encoder







Cylinders with displacement encoder Product range overview

Function	Туре	Brief description
Drives	Rodless	
	DDLI	Without guide
		With contactless measuring displacement encoder
		Based on linear drive DGC-K
	64	Supply ports on end face
	24	System product for handling and assembly technology
	DGCI	With guide
		With contactless measuring displacement encoder
	300	Based on linear drive DGC
		Supply ports optionally on end face or front
	- Carrier	System product for handling and assembly technology
	DGPI/DGPIL	Do not use for new projects!
		With or without guide
		With contactless measuring displacement encoder, integrated
	8	Wide range of options for mounting on drives
	@P	System product for handling and assembly technology
	With piston rod	
	DNCI	With contactless measuring displacement encoder
	DICI	Various piston rod variants
		Standards-based cylinder to ISO 15552
	5/	Standards bused cylinder to 150 15552
	Mary of	DIN VIDMA
	DDPC	With contactless measuring displacement encoder
		Various piston rod variants
	200	Standards-based cylinder to ISO 15552
	and	DIN
		DIN VIDMA
	DNC/DSBC	With attached potentiometer MLO-LWG
		Various piston rod variants
	200	Standards-based cylinder to ISO 15552
	.0	DIN VIDIMA
Swivel	Swivel modules	
modules	DSMI	Based on swivel modules DSM
		Integrated rotary potentiometer
		Compact design
	44	Wide range of mounting options
		as range of mounting options



Cylinders with displacement encoderProduct range overview

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3

Piston \varnothing	Stroke/swivel angle	Suitable						
	[mm/°]	for positioning v	vith	for end-position	controller	for use as a measuring		
		CPX-CMAX	SPC200	CPX-CMPX	SPC11	cylinder		
Rodless			<u>'</u>					
25, 32, 40	100, 160, 225, 300, 360,							
	450, 500, 600, 750, 850,							
	1000, 1250, 1500, 1750,							
	2000		•	•	•			
18, 25, 32,	100, 160, 225, 300, 360,							
40, 63	450, 500, 600, 750, 850,							
,	1000, 1250, 1500, 1750,							
	2000	•	•	•	•	•		
40, 50, 63	225, 300, 360, 450, 500,							
	600, 750, 1000, 1250,							
	1500, 1750, 2000	-	•	•	-	•		
With piston r	ad .							
32, 40, 50,	10 2000	1						
63	10 2000					_		
0,5		_	_	_	_	-		
	100 750							
	100 7 30	_	_	_		_		
		_	_	_	_			
80, 100	10 2000							
00, 100	10 2000	_	_	_	_	•		
						_		
	100 750							
	100 / 50	_	_	_	•	_		
		_	_	_	_			
32, 40, 50,	100, 150, 225, 300, 360,							
63, 80	450, 600, 750							
05, 00	150, 000, 750							
			•	•	•			
	I	1						
Swivel modu								
25, 40, 63	270							
		_	_	_	_	_		
		•	•		•	•		



Features

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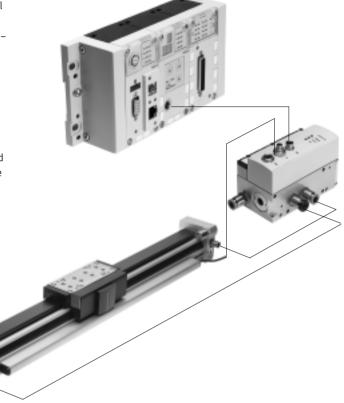
Servopneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks.

The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate to the application, can be combined in almost any way on the CPX terminal.

Advantages:

- Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- · Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alerts are all possible via TCP/IP
- Modules can be quickly exchanged and expanded without altering the wiring



Axis controller CPX-CMAX



Free choice:

Position and force control, directly actuated or selected from one of 64 configurable position sets. If you are looking for something more: the configurable function for switching to the next set enables simple functional sequences to be realised with the axis controller CPX-CMAX.

All stations are recognised as: the auto-identification function identifies each participant with its device data on the controller CPX-CMAX.

Also included:

The functional scope of the controller CPX-CMAX includes actuation of a brake or clamping unit via the proportional directional control valve VPWP.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other. Commissioning via FCT (Festo configuration software) or via fieldbus: no programming, only configuration.

Technical data → Internet: cpx-cmax

- · Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment



Features

FESTO

End-position controller CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit. Improved control of downtime. Actuation of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX.

Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal. All system data can be read and written via the fieldbus, including, for example, the mid positions.

Technical data → Internet: cpx-cmpx

Advantages:

- · Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
 - up to 30% faster cycle rates
- significantly reduced system vibration
- Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time of the machine

Proportional directional control valve VPWP



The 5/3-way proportional directional control valve for applications with Soft Stop and pneumatic positioning.
Fully digitalised – with integrated pressure sensors, with new diagnostic functions.
In sizes 4, 6, 8 and 10.
Flow rate of 350, 700, 1400 and

2000 l/min.

With switching output for actuating a brake.

Coloured supply ports.
Pre-assembled cables guarantee faultless and fast connection with the controllers CPX-CMPX and CPX-CMAX.

Technical data → Internet: vpwp

Advantages:

- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for actuating a brake/clamping unit

Measuring module CPX-CMIX



Fully digital data acquisition and transmission means that pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital measuring sensors.

Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or even for a potentiometer of the type MLO.

Technical data → Internet: cpx-cmix

- All process steps can be documented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on



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System with linear drive DDLI, DGCI



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Linear drive DDLI, DGCI with displacement encoder
- 6 Connecting cable KVI-CP-3-...

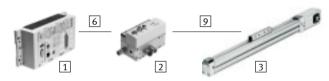
- Pneumatic rodless linear drive with displacement encoder, with or without recirculating ball bearing guide
- Displacement encoder with absolute and contactless measurement
- Diameters:
- DGCI: 18 ... 63 mm
- DDLI: 25 ... 40 mm
- Stroke: 100 ... 2000 mm in fixed lengths
- and pneumatic positioning
- Loads from 1 ... 180 kg
- No sensor interface required

Technical data → Internet: ddli or dgci

Advantages:

- · Complete drive unit
- · DDLI for easy connection to customer's guide system
- Excellent running characteristics
- For fast and accurate positioning down to ±0.2 mm (only with axis controller CPX-CMAX)

System with linear drive DGPI, DGPIL or displacement encoder MME-MTS



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Linear drive DGPI, DGPIL with displacement encoder
- 6 Connecting cable KVI-CP-3-...
- 9 NEBP-M16W6-K-2-M9W5

- Range of applications: Soft Stop

• Pneumatic rodless linear drive

or without recirculating ball

• Displacement encoder with

absolute and contactless

• Stroke: 225 ... 2000 mm in fixed

• Range of applications: Soft Stop

and pneumatic positioning

• Loads from 2 ... 180 kg · No sensor interface required

• Diameter: 25 ... 63 mm

bearing guide

measurement

lengths

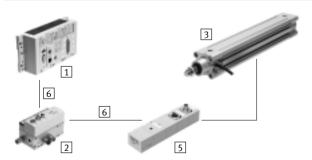
with displacement encoder, with

Technical data → Internet: dgpi

Advantages:

- · Complete drive unit
- · DGPI for easy connection to customer's guide system
- Excellent running characteristics
- · For fast and accurate positioning down to ±0.2 mm (only with axis controller CPX-CMAX)

System with standard cylinder DNCI, DDPC



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Standard cylinder DNCI, DDPC with displacement encoder
- 5 Sensor interface CASM-S-D3-R7
- 6 Connecting cable KVI-CP-3-...

- · Standard cylinder with integrated displacement encoder, conforms to DIN ISO 6432, VDMA 24 562, NF E 49 003.1 and Uni 10 290
- · Displacement encoder with contactless and incremental measuring
- Diameter: 32 ... 100 mm
- Stroke: 100 ... 750 mm
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 3 ... 450 kg and a matching sensor interface CASM-S-D3-R7
- Pre-assembled cables guarantee faultless and fast electrical connection

Technical data → Internet: dnci

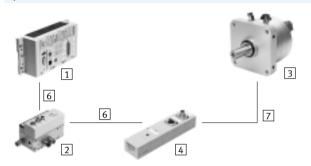
- · Compact drive unit
- Can be used universally
- Also with guide unit
- For fast and accurate positioning up to ±0.5 mm (only with axis controller CPX-CMAX)



Drive options

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System with swivel module DSMI



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Swivel module DSMI with displacement encoder
- 4 Sensor interface CASM-S-D2-R3
- 6 Connecting cable KVI-CP-3-...
- 7 Connecting cable NEBC-P1W4-K-0,3-N-M12G5

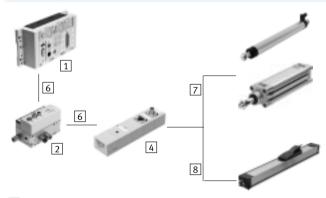
- Swivel module DSMI with integrated displacement encoder
- Identical design to pneumatic swivel module DSM
- Absolute displacement encoder based on a potentiometer
- Swivel range of 0 ... 270°
- Size: 25, 40, 63
- Max. torque: 5 ... 40 Nm
- Range of applications: Soft Stop and pneumatic positioning
- Mass moments of inertia from 15 ... 6000 kgcm² and a matching sensor interface CASM-S-D2-R3
- Pre-assembled cables guarantee faultless and fast connection with the proportional directional control valve VPWP

Technical data → Internet: dsmi

Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- With adjustable fixed stops
- For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

System with potentiometer



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 4 Sensor interface CASM-S-D2-R3
- 6 Connecting cable KVI-CP-3-...
- 7 Connecting cable NEBC-P1W4-K-0,3-N-M12G5
- 8 Connecting cable NEBC-A1W3-K-0,4-N-M12G5

Attachable potentiometers with absolute measurement, with high degree of protection

- With connecting rod or moment compensator
- Measuring range: 100 ... 2000 mm
- Pre-assembled cables guarantee faultless and fast connection with the sensor interface CASM
- Range of applications: Soft Stop and pneumatic positioning with cylinder Ø 25 ... 80 mm,
 e.g. DNC or DSBC
- Loads from 1 ... 300 kg

Technical data → Internet: casm

- Easy installation and fast commissioning
- Cost-effective
- Can also be used in harsh ambient conditions
- Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder



Cylinders with displacement encoderDrive options

System components for Soft Stop systems with end-position controller CPX-CMPX							
	Linear drive		Standard cylinder Swivel module		Displacement encoder		→ Page/
	DDLI/DGCI	DGPI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet
End-position controller					_	_	cmny
CPX-CMPX	-	-	-	-	-	-	cmpx
Prop. directional control valve	_						1,0011,00
VPWP	-	-	-	-	-	-	vpwp
Sensor interface							casm
CASM-S-D2-R3	_	_	_	-	-	_	CdSIII
Sensor interface	_	_		_	_	_	casm
CASM-S-D3-R7			_				casiii
Connecting cable							kvi
KVI-CP-3	_	_	_	_	_	_	KVI
Connecting cable	_		_		= / -	_	nebc
NEBC-P1W4	_	_	_	_	_ / -	_	HEDC
Connecting cable	_	_	_	_	- / =	_	nebc
NEBC-A1W3	_				/ -		IICDC
Connecting cable	_		_	_	_		nebp
NEBP-M16W6	_	_		_	_	_	псир

	Linear drive		Standard cylinder	Swivel module	Displacement en	coder	→ Page/
	DDLI/DGCI	DGPI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet
Axis controller		_		_	_		am av
CPX-CMAX	-	-	•	-	-	-	cmax
Prop. directional control valve				_	•		
VPWP	-	-	-	•	-	-	vpwp
Sensor interface				_			cacm
CASM-S-D2-R3	_	_	_	-	-	_	casm
Sensor interface							casm
CASM-S-D3-R7	_	_	-	_	_	_	Casiii
Connecting cable	_			_			kvi
KVI-CP-3	_	-	_	-	-	-	KVI
Connecting cable					■/-		nebc
NEBC-P1W4	_	_	_	-	- / -	_	lienc
Connecting cable	_	_	_	_	-/ ■	_	nebc
NEBC-A1W3	_	_	_	_	- / -	_	lienc
Connecting cable							nebp
NEBP-M16W6	_	-	_	_	_	-	перр

System components for measuring cylinders with measuring module CPX-CMIX							
	Linear drive		Standard cylinder	Standard cylinder Swivel module		Displacement encoder	
	DDLI/DGCI	DGPI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet
Measuring module	_		•	_	_	_	
CPX-CMIX-M1-1	-	-	•	•	-	-	cmix
Sensor interface				_			cacm
CASM-S-D2-R3	_	_	_	-	-	_	casm
Sensor interface							cacm
CASM-S-D3-R7	_	_	-			_	casm
Connecting cable	(■) ¹⁾	(■) 1)	•	•		(■)	kvi
KVI-CP-3	(=) /	(=) /	_	_	_	(-)	KVI
Connecting cable	_		_	_	I / -	_	nebc
NEBC-P1W4			_	-	- /-		HEDC
Connecting cable	_	_	_		- / ■	_	nebc
NEBC-A1W3	_	_		-	, –		TICDC
Connecting cable	_		_	_	_		nebp
NEBP-M16W6	_	_		-		_	псир

¹⁾ As an extension

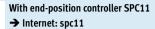


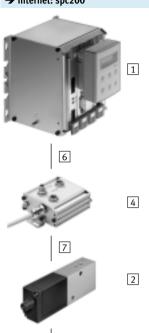
Overview

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Individual components for positioning With axis controller SPC200

→ Internet: spc200

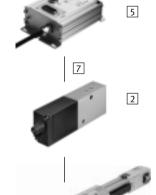






- 2 Proportional directional control valve MPYE
- 3 Linear drive DGPI, DGPIL
- 4 Axis interface SPC-AIF-MTS
- 6 Connecting cable KSPC-AIF-...
- 7 Connecting cable KMPYE-AIF-...

3



- 2 Proportional directional control valve MPYE
- 3 Linear drive DGPI, DGPIL
- 5 End-position controller SPC11-MTS-AIF
- 7 Connecting cable KMPYE-AIF-...

DGPI, without guide

- $\bullet~$ Piston \varnothing 40 ... 63 mm
- Stroke 225 ... 2,000 mm
- Standard moment compensator
- Low characteristic load values
- Supply ports on both sides



3

DGPIL, with recirculating ball bearing guide

- Piston Ø 40 ... 63 mm
- Stroke 225 ... 2,000 mm
- Standard slide
- High characteristic load values
- Supply ports on both sides



10

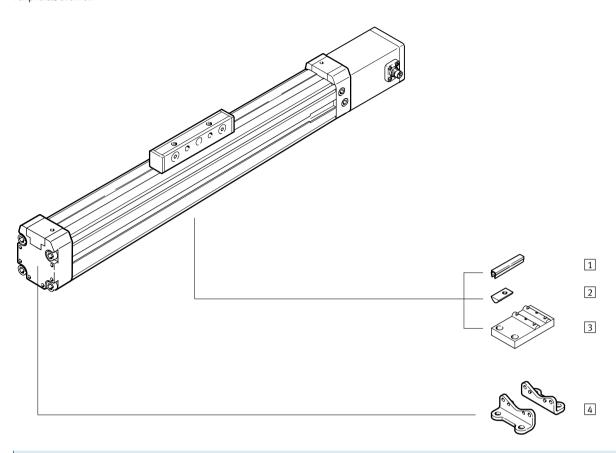
22



Linear drives DGPI, with integrated displacement encoder Peripherals overview

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10



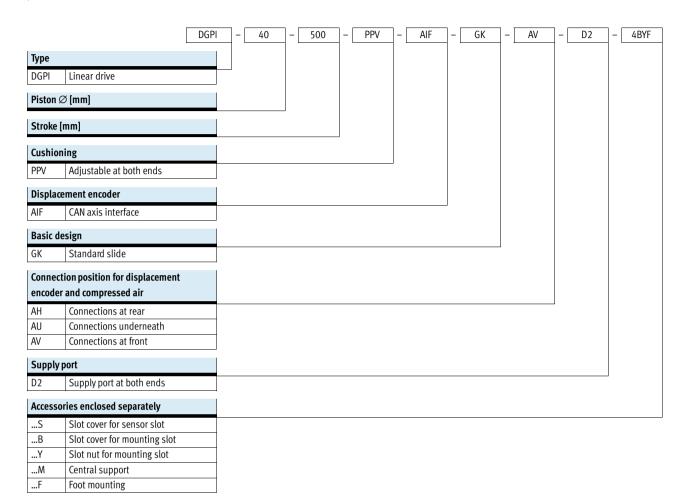
Varian	Variants and accessories						
	Туре	Brief description	→ Page/Internet				
1	Slot cover	For protecting against the ingress of dirt	39				
	B/S						
2	Slot nut	For mounting attachments	39				
	Υ						
3	Central support	For mounting the axis	36				
	M						
4	Foot mounting	For mounting the axis	36				
	F						
	Adapters	For drive/drive combinations	42				
		For drive/gripper combinations	gripper				



Linear drives DGPI, with integrated displacement encoder

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Type codes

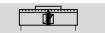




Linear drives DGPI, with integrated displacement encoder

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Function





Diameter 25 ... 63 mm



Stroke length 225 ... 2,000 mm



General technical data						
Piston ∅		40	50	63		
Design		Piston				
		Moment compensator				
		Profile barrel				
Mode of operation		Double-acting				
Operating medium ¹⁾		Compressed air according to ISO	8573-1:2010 [6:4:4]			
Note about the operating/pilot medium		Lubricated operation not possible				
		Pressure dew point 10 °C below ambient temperature/temperature of medium				
Cushioning		Adjustable at both ends				
Cushioning length	[mm]	30				
Position sensing		Integrated displacement encoder				
Measuring principle		Digital, magnetostrictive, non-contacting and absolute measurement				
Type of mounting		Foot mounting				
Stroke ²⁾³⁾	[mm]	225; 300; 360; 450; 500; 600; 750; 1,000; 1,250; 1,500; 1,750; 2,000				
Pneumatic connection		G1/4		G3/8		
Electrical connection		6-pin round plug to DIN 45322				

- The proportional directional control valve MPYE used requires the characteristic values.
- Note stroke reduction in combination with SPC200.
- Supply of compressed air to each end of the cylinder (feature D2) is absolutely essential for Soft Stop SPC11 and axis controller SPC200 as of a length of 500 mm.

Forces [N] and impact energy [Nm]						
Piston \varnothing	40	50	63			
Theoretical force at 6 bar	754	1,178	1,870			
Max. impact energy in the end positions ¹⁾	0.4	0.8	0.8			

1) Cushioning PPV must be completely open for applications with Soft Stop SPC11 and axis controller SPC200.

Permissible impact velocity:

$$v_{\text{perm.}} = \sqrt{\frac{2 \times E_{\text{perm.}}}{m_{\text{dead}} + m_{\text{load}}}}$$

Permissible impact velocity V_{perm}. Maximum impact energy E_{perm.} Moving mass (drive) m_{dead} m_{load} Moving effective load

$$m_{load} = \frac{2 \times E_{perm.}}{V^2} - m_{dead}$$

These specifications represent the maximum values that can be achieved. Note the maximum permissible impact energy.



Linear drives DGPI, with integrated displacement encoder

Positioning characteristics with axis controller SPC200						
Piston ∅		40	50	63		
Repetition accuracy	[mm]	→ 14				
Mounting position		Any				
Minimum load, horizontal ¹⁾	[kg]	5	8	12		
Maximum load, horizontal ¹⁾	[kg]	75	120	180		
Minimum load, vertical ¹⁾	[kg]	5	8	12		
Maximum load, vertical ¹⁾	[kg]	25	40	60		
Minimum travel speed	[m/s]	0.05	<u>.</u>			
Maximum travel speed	[m/s]	3				
Typical positioning time, long stroke ²⁾	[s]	0.75/1.20	0.95/1.25	0.90/1.20		
Typical positioning time, short stroke ³⁾	[s]	0.40/0.60	0.50/0.65	0.50/0.65		
Minimum positioning stroke ⁴⁾	[%]	3	<u> </u>			
Stroke reduction ⁵⁾	[mm]	35				
Recommended proportional directional control valve		→ 40	→ 40			

- 1) Load = effective load + mass of all moving parts on the drive
- 2) At 6 bar, horizontal mounting position, DGPL-XX-1250, 1,000 mm travel at min./max. load 3) At 6 bar, horizontal mounting position, DNCM-XX-1250, 100 mm travel at min./max. load
- 4) In relation to the maximum stroke of the drive, but never more than 20 mm
- 5) The stroke reduction must be maintained on each side of the drive, the max. positionable stroke is therefore: stroke 2x stroke reduction

Positioning characteristics with end-position controller SPC11							
$Piston\varnothing$		40	50	63			
Repetition accuracy of a mid-position ¹⁾	[mm]	±2					
Mounting position		Any					
Minimum load, horizontal ²⁾	[kg]	5	8	12			
Maximum load, horizontal ²⁾	[kg]	75	120	180			
Minimum load, vertical ²⁾	[kg]	5	8	12			
Maximum load, vertical ²⁾	[kg]	25	40	60			
Travel time	[s]	→ SoftStop sizing	→ SoftStop sizing software: → www.festo.com				
Recommended proportional directional control valve		→ 40					

- 1) In the stroke range from 225 ... 2,000 mm
- 2) Load = effective load + mass of all moving parts on the drive

Operating and environmental conditions							
Piston \varnothing		40	50	63			
Operating pressure ¹⁾	[bar]	4 8					
Ambient temperature	[°C]	-10 +60	-10 +60				
Vibration resistance	To DIN/IEC 68 Parts	To DIN/IEC 68 Parts 2 – 6, severity level 1					
Continuous shock resistance		To DIN/IEC 68 Parts	To DIN/IEC 68 Parts 2 – 27, severity level 1				
CE marking (see declaration of conformity)	To EU EMC Directiv	To EU EMC Directive					
Protection class (displacement encoder)	IP65 to IEC 60 529	IP65 to IEC 60 529					
Corrosion resistance class CRC ²⁾	1	1					

- Only applies to applications with Soft Stop SPC11 and axis controller SPC200
 CRC1: Corrosion resistance class to Festo standard 940 070
- Components with light corrosion exposure. Protection for transport and storage. Components without significant decorative function or surface, e.g. installed out of sight internally or behind covers.

Weight [g]							
Piston \varnothing	40	50	63				
Basic weight	3,500	6,980	10,600				
Additional weight per 10 mm stroke	59	130	168				
Moving load	551	1,045	1,775				



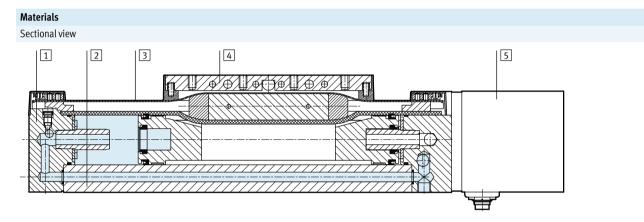
Linear drives DGPI, with integrated displacement encoder

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Technical data

Electrical data – Displaceme	ent encoder		
Power supply		[V DC]	24 (-15/+25%)
Maximum current consumpti	ion	[mA]	90
Resolution		[mm]	≤0.01
Independent linearity ¹⁾	Maximum	[%]	0.02
Temperature coefficient		[ppm/°K]	≤15
Interface			Digital, CAN with protocol: SPC-AIF

1) Minimum ±50 μm



Drive		
1	End cap	Anodised aluminium
2	Profile	Anodised aluminium
3	Cover strip	Corrosion-resistant steel
4	Moment compensator	Anodised aluminium
5	Displacement encoder housing	Anodised aluminium
-	Seals	Nitrile rubber, polyurethane



Repetition accuracy Tolerance t [mm] as a function of stroke l [mm] Vertical Horizontal 1.0 1.0 8.0 1 8.0 0.6 † [mm] † [mm] 0.6 0.4 0.4 0.2 0.2 0 500 2000 2500 ó 200 500 2000 2500 l [mm] l [mm]

- 1 With analogue displacement encoder
- 2 With digital displacement encoder



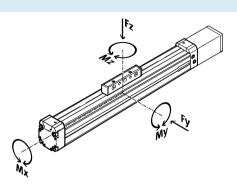
Linear drives DGPI, with integrated displacement encoder

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Technical data

Characteristic load values

The indicated forces and torques refer to the centre line of the internal diameter of the profile barrel. These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



If the drive is simultaneously subjected to several of the indicated forces and torques, the following equation must be satisfied in addition to the indicated maximum loads:

$$0,4\times\frac{Fz}{Fz_{max.}}+\frac{Mx}{Mx_{max.}}+\frac{My}{My_{max.}}+0,2\times\frac{Mz}{Mz_{max.}}\leq1$$

$$\frac{Fz}{Fz_{max.}} \le 1$$
 $\frac{Mz}{Mz_{max.}} \le 1$

Permissible forces	and torques				
Piston ∅		40	50	63	
Fy _{max} .	[N]	0	0	0	
Fz _{max} .	[N]	800	1,200	1,600	
Mx _{max} .	[Nm]	4	7	8	
My _{max} .	[Nm]	60	120	120	
Mz _{max} .	[Nm]	8	15	24	

Maximum permissible support span l as a function of force F

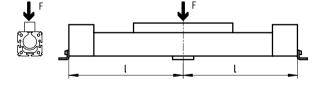
The axis may need to be supported with central supports MUP in order to

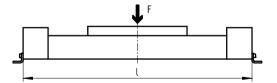
limit deflection in the case of large strokes. The following graphs can be

used to determine the maximum permissible support span l as a function

of force F acting on the axis.

Force on the surface of the slide





Maximum support span I (without central support) as a function of force F

Piston Ø 40 4 10000 □

1000 DGPI...-40 DGPI...-25

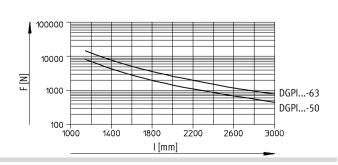
2000

2500

1500

l [mm]

Piston Ø 50/63



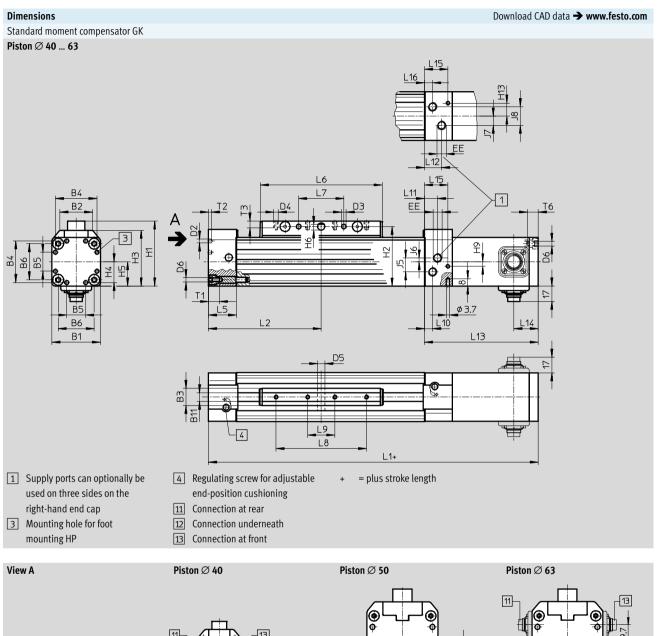
1 † 500

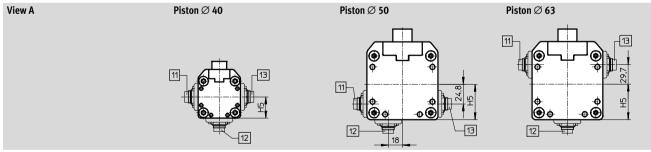


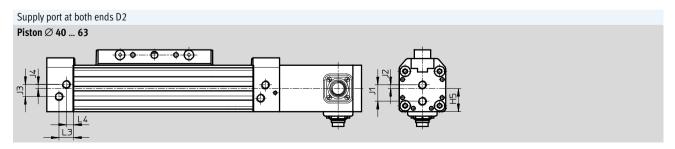
Linear drives DGPI, with integrated displacement encoder

FESTO

Technical data





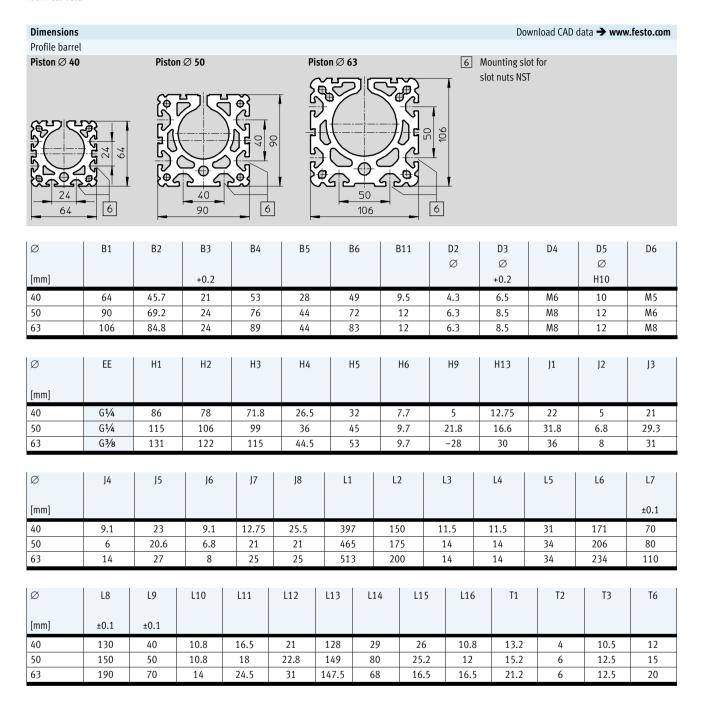




Linear drives DGPI, with integrated displacement encoder

FESTO

Technical data





Linear drives DGPI, with integrated displacement encoder

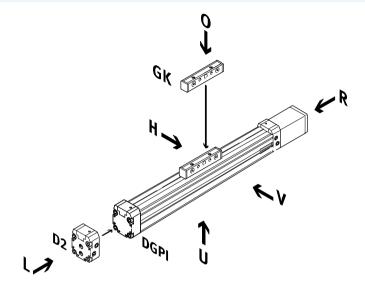
FESTO

Ordering data - Modular products

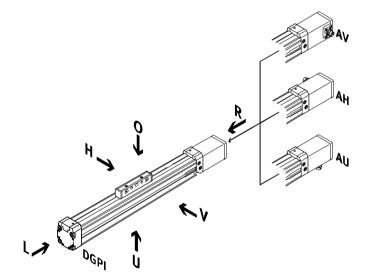
Order code

Mandatory data/options

- D2 Supply port at both ends
- GK Standard slide

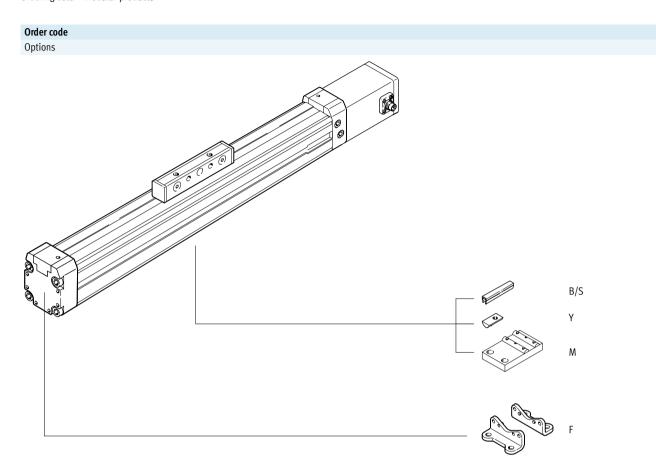


- AV Displacement encoder connection at front
- AH Displacement encoder connection at rear
- AU Displacement encoder connection underneath





Linear drives DGPI, with integrated displacement encoder Ordering data – Modular products





Linear drives DGPI, with integrated displacement encoder Ordering data – Modular products

Module No.	Function	Size	Stroke	Cushi	Displacement encoder	Basic design	f	Connection ¡ for displace: encoder	
175136	DGPI	40	225 2	,000 PPV	AIF	GK	/	AH	
175137		50					/	AU	
175138		63					A	AV	
Ordering									
example									
175138	DGPI	- 63	– 750	– PPV	– AIF	– GK	- 1	AV	
rdering table ize		40	5	0	63		Condi- tions	Code	Enter
Module No.		175136	1	75137	175138				0000
Function		Pneumatic linear di	ive with integra	ated displacement	encoder			DGPI	DGPI
Size		40	5	0	63				
Stroke	[mm]	225; 300; 360; 45	0; 500; 600; 7	50; 1,000; 1,250;	1,500; 1,750; 2,000				
Cushioning		Pneumatic cushion	ing, adjustable	at both ends				-PPV	-PPV
Displacemen	nt encoder	Temposonic with CA	N axis interfac	e				-AIF	-AIF
Basic design		Standard piston/sli	de					-GK	-GK
	Connection position for Connection position for disp			placement encoder and supply port, rear					
0	position for	Connection position	n for displacem	ent encoder and si	ıpply port, rear			-AH	
Connection	position for nt encoder AIF		•		upply port, rear upply port, underneath			-AH -AU	

Transfer order cod	le						
	DGPI	-	_	- PPV	– AIF	– GK	_



Linear drives DGPI, with integrated displacement encoder Ordering data – Modular products

Supply port	Accessories	Slot cover	Slot nut	Central support	Foot mounting
D2	ZUB	S B	Y	M	F
	: ZUB	- 2B2S	10Y		F
dering table					

Ore	dering table								
Siz	e		40	50	63	Condi-	Code	En	nter
						tions		СО	ode
Ψ	Supply port		At both ends				-D2		
	Accessories		Enclosed separately				:ZUB-	:Zl	'UB-
	Slot cover,	Sensor slot	1 10				S		
	2 pcs., 0.5 m								
		Mounting	1 10				В		
		slot							
	Slot nut	Mounting	1 10				Ү		
		slot							
	Central support		1 10				M		
	Foot mounting		1 10				F		

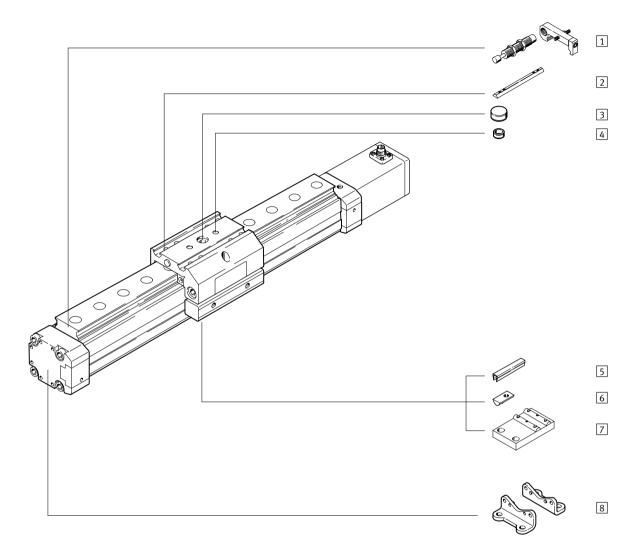
	Transfer order code							
-[:	ZUB -	-	ſ	Ī		1



Linear drives DGPIL, with integrated displacement encoder

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Peripherals overview





Linear drives DGPIL, with integrated displacement encoder Peripherals overview

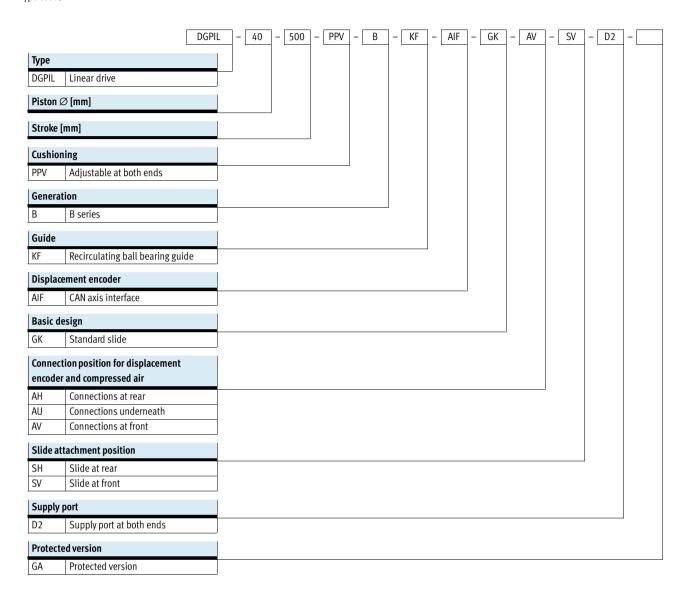
Varia	nts and accessories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber kit	For avoiding damage at the end stop in the event of malfunction	38
	C/E		
2	Slot nut for slide	For mounting loads and attachments on the slide	39
	X		
3	Central mounting	For centring loads and attachments on the slide	39
	Q		
4	Centring sleeves	For centring loads and attachments on the slide	39
	Z		
5	Slot cover	For protecting against the ingress of dirt	39
	B/S		
6	Slot nut for mounting slot	For mounting attachments	39
	Υ		
7	Central support	For mounting the axis	36
	M		
8	Foot mounting	For mounting the axis	36
	F		



Linear drives DGPIL, with integrated displacement encoder

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Type codes

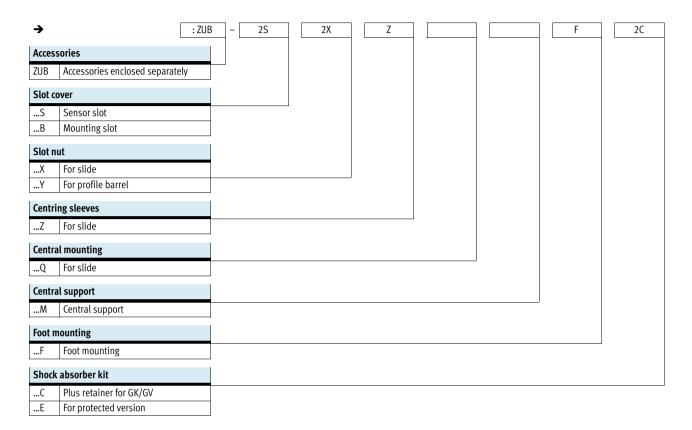




Linear drives DGPIL, with integrated displacement encoder

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Type codes



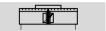


Linear drives DGPIL, with integrated displacement encoder

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Technical data

Function





Diameter 40 ... 63 mm



Stroke length 225 ... 2,000 mm



General technical data				
Piston ∅		40	50	63
Design		Piston		
		Moment compensator		
		Profile barrel		
Mode of operation		Double-acting		
Operating medium ¹⁾		Compressed air according	to ISO 8573-1:2010 [6:4	:4]
Note about the operating/pilot medium		Lubricated operation not	possible	
		Pressure dew point 10 °C	below ambient temperatu	re/temperature of medium
Cushioning		Adjustable at both ends		
Cushioning length	[mm]	30		
Position sensing		Integrated displacement	encoder	
Measuring principle		Digital, magnetostrictive,	non-contacting and absol	ute measurement
Type of mounting		Foot mounting		
Stroke ²⁾³⁾	[mm]	225; 300; 360; 450; 500	; 600; 750; 1,000; 1,250	9; 1,500; 1,750; 2,000
Protection against rotation/guide		Guide rail with slide		
		Recirculating ball bearing		
Protected version ⁴⁾		Optional		
Pneumatic connection		G1/4		G3/8
Electrical connection		6-pin round plug to DIN 4	5322	<u>, </u>

- 1) The proportional directional control valve MPYE used requires the characteristic values.
- Note stroke reduction in combination with SPC200.
- Supply of compressed air to each end of the cylinder (feature D2) is absolutely essential for Soft Stop SPC11 and axis controller SPC200 as of a length of 500 mm.
- 4) Protected against particles from above and the side.

Forces [N] and impact energy [Nm]			
Piston \varnothing	40	50	63
Theoretical force at 6 bar	754	1,178	1,870
Max. impact energy in the end positions ¹⁾	0.4	0.8	0.8

1) Cushioning PPV must be completely open for applications with Soft Stop SPC11 and axis controller SPC200.

Permissible impact velocity:

$$v_{perm.} = \sqrt{\frac{2 \times E_{perm.}}{m_{dead} + m_{load}}}$$

 v_{perm.}
 Permissible impact velocity

 E_{perm.}
 Maximum impact energy

 m_{dead}
 Moving mass (drive)

 m_{load}
 Moving effective load

Maximum permissible load:

$$m_{load} = \frac{2 \times E_{perm.}}{V^2} - m_{dead}$$

Moving mass (drive)

Moving effective load

maximum values that can be achieved. Note the maximum permissible impact energy.



Linear drives DGPIL, with integrated displacement encoder

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Positioning characteristics with axis control	oller SPC200			
Piston ∅		40	50	63
Repetition accuracy	[mm]	→ 14		
Mounting position		Any		
Minimum load, horizontal ¹⁾	[kg]	5	8	12
Maximum load, horizontal ¹⁾	[kg]	75	120	180
Minimum load, vertical ¹⁾	[kg]	5	8	12
Maximum load, vertical ¹⁾	[kg]	25	40	60
Minimum travel speed	[m/s]	0.05		
Maximum travel speed	[m/s]	3		
Typical positioning time, long stroke ²⁾	[s]	0.75/1.20	0.95/1.25	0.90/1.20
Typical positioning time, short stroke ³⁾	[s]	0.40/0.60	0.50/0.65	0.50/0.65
Minimum positioning stroke ⁴⁾	[%]	3	<u>.</u>	·
Stroke reduction ⁵⁾	[mm]	35		
Recommended proportional directional con	trol valve	→ 40		

- 1) Load = effective load + mass of all moving parts on the drive

- 1) Load = effective load + fliads of an informing parts of in drive
 2) At 6 bar, horizontal mounting position, DSPL-XX-1250, 1,000 mm travel at min./max. load
 3) At 6 bar, horizontal mounting position, DNCM-XX-1250, 100 mm travel at min./max. load
 4) In relation to the maximum stroke of the drive, but never more than 20 mm
 5) The stroke reduction must be maintained on each side of the drive, the max. positionable stroke is therefore: stroke 2x stroke reduction

Positioning characteristics with end-positi	on controller S	PC11		
Piston \varnothing		40	50	63
Repetition accuracy of a mid-position ¹⁾	[mm]	±2		
Mounting position		Any		
Minimum load, horizontal ²⁾	[kg]	5	8	12
Maximum load, horizontal ²⁾	[kg]	75	120	180
Minimum load, vertical ²⁾	[kg]	5	8	12
Maximum load, vertical ²⁾	[kg]	25	40	60
Travel time	[s]	→ SoftStop sizing	g software: → www.festo.com	
Recommended proportional directional con-	trol valve	→ 40		

- 1) In the stroke range from 225 ... 2,000 mm
- 2) Load = effective load + mass of all moving parts on the drive

Operating and environmental condition	ons			
Piston \varnothing		40	50	63
Operating pressure ¹⁾	[bar]	4 8		
Ambient temperature	[°C]	-10 +60		
Vibration resistance		To DIN/IEC 68 Pa	rts 2 – 6, severity level 1	
Continuous shock resistance		To DIN/IEC 68 Pa	rts 2 – 27, severity level 1	
CE marking (see declaration of conform	ity)	To EU EMC Direct	ive	
Protection class (displacement encode	r)	IP65 to IEC 60 52	29	

1) Only applies to applications with Soft Stop SPC11 and axis controller SPC200



Linear drives DGPIL, with integrated displacement encoder Technical data

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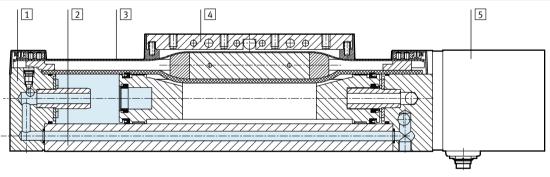
Weight [g]				
$Piston\varnothing$	40	50	63	
Standard slide GK				
Basic weight	5,330	10,700	16,870	
Additional weight per 10 mm stroke	99	186	256	
Moving load	1,700	3,000	4,990	-
Additional weights with protected version GA				
Dirt protection cover	4,000	-	_	
Additional weight per 10 mm stroke	65	-	-	-
Moving load	2,550	-	-	

Electrical data – Displaceme	nt encoder		
Power supply		[V DC]	24 (-15/+25%)
Maximum current consumption	on	[mA]	90
Resolution		[mm]	≤ 0.01
Independent linearity ¹⁾	Maximum	[%]	0.02
Temperature coefficient		[ppm/°K]	≤15
Interface			Digital, CAN with protocol: SPC-AIF

¹⁾ Minimum $\pm 50 \ \mu m$

Materials

Sectional view



Drive	2	
1	End cap	Anodised aluminium
2	Profile	Anodised aluminium
3	Cover strip	Corrosion-resistant steel
4	Moment compensator	Anodised aluminium
5	Displacement encoder housing	Anodised aluminium
-	Slide	Anodised aluminium
-	Guide rail	Corrosion-resistant steel
-	Seals	Nitrile rubber, polyurethane



Note

More technical data

→ Internet: dpgl



Linear drives DGPIL, with integrated displacement encoder

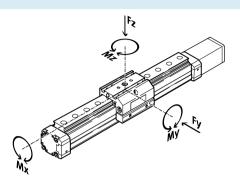
FESTO

Technical data

Characteristic load values

The indicated forces and torques refer to the centre line of the internal diameter of the profile barrel.

These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



If the drive is simultaneously subjected to several of the indicated forces and torques, the following equation must be satisfied in addition to the indicated maximum loads:

$$\frac{Fy}{Fy_{max.}} + \frac{Fz}{Fz_{max.}} + \frac{Mx}{Mx_{max.}} + \frac{My}{My_{max.}} + \frac{Mz}{Mz_{max.}} \leq 1$$

Permissible forces	and torques				
Piston \varnothing		40	50	63	
Fy _{max} .	[N]	7,300	7,300	14,050	
Fz _{max} .	[N]	7,300	7,300	14,050	
Mx _{max} .	[Nm]	170	240	580	
My _{max} .	[Nm]	330	460	910	
Mz _{max} .	[Nm]	330	460	910	



Linear drives DGPIL, with integrated displacement encoder

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Technical data

Maximum permissible support span l as a function of force F

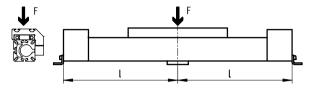
The axis may need to be supported with central supports MUP in order to

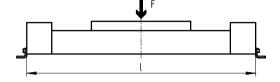
limit deflection in the case of large strokes. The following graphs can be

used to determine the maximum permissible support span l as a function

of force F acting on the axis.

Force on the surface of the slide

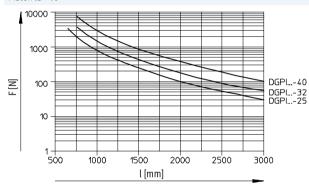


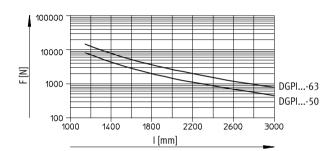


Maximum support span I (without central support) as a function of force F

Piston Ø 40

Piston Ø 50/63



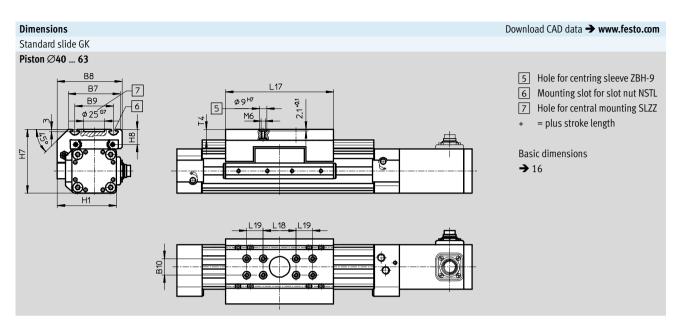


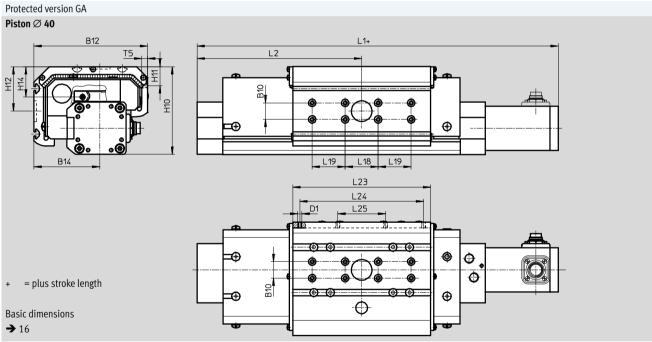


Linear drives DGPIL, with integrated displacement encoder

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Technical data





Ø	B7	B8	В9	B10	B12	B14	D1	H1	H7	H8	H10
[mm]				±0.03							
40	78.5	96.5	55 ±0.2	20	137.6	79.6	M5	86	90.5	20	106.6
50	97	122	72 ±0.2	40	-	_	-	115	122.5	26	-
63	121	142	90 ±0.25	40	-	-	-	131	144.5	30	-

Ø	H11	H12	H14	L1	L2	L17	L18	L19	L23	L24	L25	T4	T5
[mm]						+0.2	±0.03	±0.03				max.	
40	23.1	54	36.1	397	150	167	40	40	167	150	58	12.5	7
50	-	ı	-	465	175	202	40	40	ı	-	-	18.5	-
63	-	ı	-	513	200	230	40	40	ı	-	-	20.5	-



Linear drives DGPIL, with integrated displacement encoder

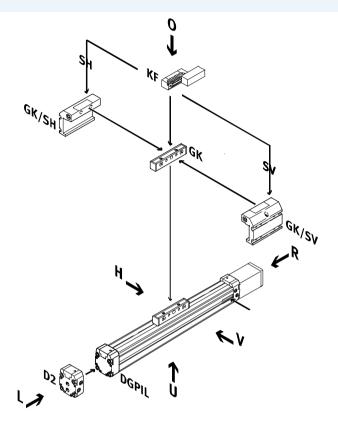
FESTO

Ordering data - Modular products

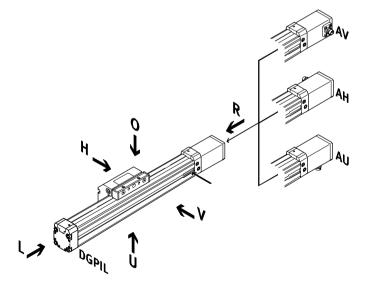
Order code

Mandatory data

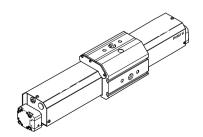
- KF Recirculating ball bearing guide
- SH Slide at rear
- SV Slide at front
- D2 Supply port at both ends
- GK Standard slide



- AV Displacement encoder connection to front
- AH Displacement encoder connection to rear
- AU Displacement encoder connection underneath

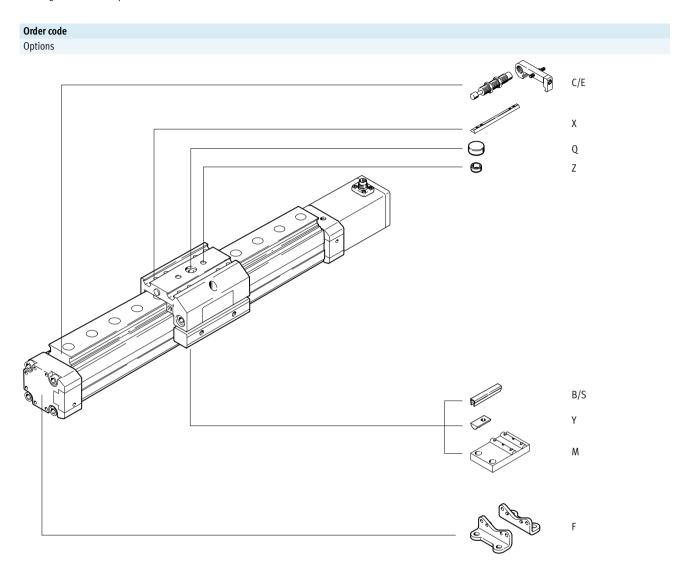


GA Protected version





Linear drives DGPIL, with integrated displacement encoder Ordering data – Modular products





Linear drives DGPIL, with integrated displacement encoder Ordering data – Modular products

M	Mandatory	data												
Mod	dule No.	Function	Size	Stroke	Cush- ioning	Gener- ation	Guide	Displace- ment encoder	Basic design	t	Connection ion for dis	place-	tach	e at- iment ition
175	5136	DGPIL	40	225	PPV	В	KF	AIF	GK	A	ιΗ		SH	
175	5137		50	2,000						A	λU		SV	
175	5138		63							A	W			
	ering													
	mple 5138	DGPIL	- 63	- 450	- PPV	- В	- KF	- AIF	– GK	_ 4	\U	_	SH	
Orderi	ing table													
Size	ing table		40		50			63			Condi-	Code		Enter
											tions			code
ΛМ	odule No.		175136		17513	37		175138						
Fu	ınction		Pneumatic	linear drive wi	th integrated	displaceme	nt encoder	and slide				DGPIL		DGPIL
Si	ize		40		50			63						
St	troke	[mm]	225; 300;	360; 450; 500	; 600; 750; 1	1,000; 1,25	0; 1,500; 1	,750; 2,000						
Cu	ushioning		Pneumatic	cushioning, ac	ljustable at b	oth ends						-PPV		-PPV
Ge	eneration		B series									-B		-B
Gu	uide		Recirculati	ng ball bearing	guide							-KF		-KF
Di	isplacement	encoder	Temposoni	ic with CAN axis	interface							-AIF		-AIF
	asic design		Standard p	oiston/slide								-GK		-GK
	onnection po			n position for d	•							-AH		
	isplacement		Connection	n position for d	splacement e	encoder and	supply por	t, underneath				-AU		
an	nd compress	ed air	Connection	n position for d	splacement e	encoder and	supply por	t, front				-AV		
	lide attachment position Slide at rea		ar								-SH			
			Slide at fro	ont								-SV		

Transfer order co	d	е															
	Ш	DGPIL	-	 -	_	PPV	-	В	_	KF	_	AIF	_	GK	_	-	



Linear drives DGPIL, with integrated displacement encoder

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Ordering data – Modular products

O Options									
Supply port	Protected version	Acces- sories	Slot cover	Slot nut	Centring sleeve	Central support	Central mounting	Foot mounting	Shock absorber
D2	GA	ZUB	S B	X Y	Z	M	Q	F	C E
- D2 -	- :	ZUB -	2S2B	2X				F	2C

rdering table							
ize		40	50	63	Condi- tions	Code	Enter code
Supply port		At both ends				-D2	
Protected vers	ion	Protected roller design for				-GA	
		harsh environment					
Accessories		Enclosed separately				:ZUB-	:ZUB-
Slot cover,	Sensor slot	1 10				S	
2 pcs., 0.5 m							
	Mounting	1 10				В	
	slot						
Slot nut	Slide	1 10				X	
	Mounting	1 10				Ү	
	slot						
Centring sleeve	e (pack of 10)	10, 20, 30, 40, 50, 60, 70, 80), 90			Z	
Central suppor		1 10				M	
Central mount	ing	1 10				Q	
Foot mounting		1 10				F	
Shock	With	1 10			1	C	
absorber kit	retainer,						
	1-fold						
		1 10	-	-	2	Е	

1 C N	with protected version (ŝΑ.
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² **E** Only with protected version GA.



Linear drives DGPL/DGPI/DGPIL Accessories

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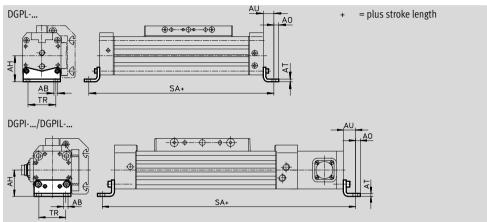
Foot mounting HP

(order code: F)





Free of copper, PTFE and silicone



Dimensions a	Dimensions and ordering data										
For Ø	AB	AH	AO	AT	AU	9	SA	TR	Weight	Part No.	Туре
	Ø					DGPL	DGPI(L)				
[mm]									[g]		
40	6.6	46	8.5	5	17.5	335	432	45	188	150733	HP-40
50	9	61	11	6	25	400	515	65	243	150734	HP-50
63	11	69	13.5	6	28	456	569	75	305	150735	HP-63

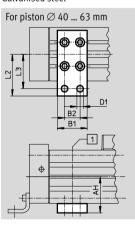
Central support MUP

(order code: M)



Material:

Galvanised steel



Free of copper, PTFE and silicone

1 Position of the central support along the profile barrel is freely selectable. Please note span.

Dimensions a	Dimensions and ordering data											
For \varnothing	AH	B1	B2	D1	L2	L3	Weight	Part No.	Туре			
				Ø								
[mm]							[g]					
40	46	35	22	6.6	47	40	126	150738	MUP-40			
50	61	50	26	11	70	58	241	150739	MUP-50			
63	69	50	26	11	77	65	340	150800	MUP-63			



Linear drives DGPL/DGPI/DGPIL Accessories

Shock absorber DG-GA

for DGPIL

Protected version GA

(order code: E)

Materials:

Housing: Galvanised steel

Piston rod: High-alloy steel

Seals: NBR, PUR

Free of copper, PTFE and silicone



Ordering data			
For Ø	Weight	Part No.	Туре
[mm]	[g]		
40	140	192877	DG-GA-40-YSR

Shock absorber YSR-...-C

for DGPL/DGPIL

(order code: C)

Materials:

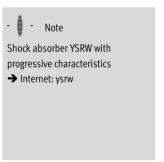
Housing: Galvanised steel

Piston rod: High-alloy steel

Seals: NBR, PUR

Free of copper, PTFE and silicone





Weight	Part No.	Туре
[g]		
140	34573	YSR-16-20-C
140	34573	YSR-16-20-C
240	34574	YSR-20-25-C
	[g] 140 140	Weight [g] Part No. 140 34573 140 34573



Linear drives DGPL/DGPI/DGPIL Accessories

FESTO

Shock absorber retainer KYP

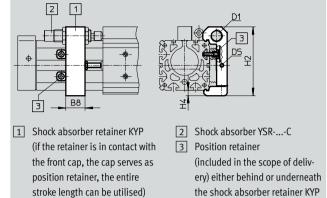
for DGPL/DGPIL (order code: C)

Materials:

Retainer: Aluminium

Sleeve: Corrosion-resistant steel





Dimensions a	Dimensions and ordering data											
For \varnothing	B8	D1	D5	H2	H4	Weight	Part No.	Туре				
[mm]						[g]						
40	32	M22x1.5	M5	102	8	209	158910	KYP-40				
50	35	M22x1.5	M8	124	10	415	158911	KYP-50				
63	44	M26x1.5	M10	152.5	11.5	609	158912	KYP-63				

Ordering data – Push-in fittings				Technical data → Internet: qui	ick star
	For Ø	Comment	Part No.	Туре	PU ¹⁾
	[mm]				
	40, 50	For connecting compressed air tubing with standard	186099	QS-G ¹ / ₄ -8	10
		O.D.	186101	QS-G ¹ / ₄ -10	
	63		186100	QS-G3/8-8	
			186102	QS-G3/8-10	
			186103	QS-G3/8-12	

1) Packaging unit



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Ordering data				Technical	data → Internet: moun	ting component
	For Ø	Comment	Order code	Part No.	Туре	PU ¹⁾
	[mm]					
Slot nut NST	·		·			· ·
√ 0>	40	For mounting slot	Υ	150914	NST-5-M5	1
	50, 63			150915	NST-8-M6	
Slot nut NSTL						
(a)	40	For slide	X	158412	NSTL-40	1
	50			158413	NSTL-50	
	63			158414	NSTL-63	
(3)						
Centring sleeve ZBH						
\bigcirc	40 63	For slide	Z	150927	ZBH-9	10
<u>U</u>						
Central mounting SLZZ						
. 1	40	For slide	Q	150901	SLZZ-25/16	1
	50, 63			150904	SLZZ-50/40	
		-		<u> </u>		
Slot cover ABP						
Siot cover ADP	40	For mounting slot	В	151681	ABP-5	2
	50, 63	Every 0.5 m	В	151682	ABP-8	
	50, 65	Every 0.3 III		151062	ADF-0	
	I					
Slot cover ABP-S						
	40 63	For sensor slot	S	563360	ABP-5-S1	2
		Every 0.5 m				

¹⁾ Packaging unit



Linear drives DGPL/DGPI/DGPIL Accessories

FESTO

Selection aid													
Application	For Ø	Stroke [mm]											
	[mm]	225	300	360	450	500	600	750	1,000	1,250	1,500	1,750	2,000
lorizontal/vertical	For applicati	For applications with axis controller SPC200											
	40	1/1	2/2	2/2	2/2	2/2	2/2	2/2	3/3	3/3	3/3	3/3	3/3
	50	2/2	2/2	2/2	2/2	2/2	3/3	3/3	3/3	3/3	3/3	3/3	3/3
	63	3/3	3/3	3/3	3/3	3/3	3/3	3/3	3/3	4/4	4/4	4/4	4/4
		For applications with Soft Stop end-position controller SPC11											
	40	2/1	2/1	2/1	2/1	2/2	3/3	3/4	3/4	3/4	3/4	3/4	3/4
	50	1/1	2/1	2/2	3/2	3/3	4/3	4/4	4/4	4/4	4/4	4/4	4/4
	63	2/1	2/2	3/3	3/3	4/4	4/4	4/4	4/4	4/4	4/4	4/4	4/4
			II.										
alve alve	Selection nu	mber							Part No	. Type			
	1								15169	2 MPYI	E-5-1/8-LF-(010-B	
6	2	2								151693 MPYE-5-1/8-HF-010-B			
	3	3									151694 MPYE-5-1/4-010-B		
	4								15169	5 MPYI	E-5-3/8-010	D-B	



Note

The representation e.g. 2/1 in the columns means:

Selection number 2 Selection number 1 for horizontal application for vertical application 151 693 MPYE-5-1/8-HF-010-B 151 692 MPYE-5-1/8-LF-010-B



Linear drives DGPL/DGPI/DGPIL Accessories

Ordering data	a – Proximity sensor for T-slot, magnetic r	eed				Technical data → Internet: sme
	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part No.	Туре
N/O contact						
N. C.	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150857	SME-8-S-LED-24
N/C contact						
N.	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	7.5	160251	SME-8-O-K-LED-24
	with the cylinder profile					
Ordoring data	a – Proximity sensor for T-slot, magneto-r	ocietivo				Technical data → Internet: sm
Ordering data	Type of mounting	Switching	Electrical connection	Cable length	Part No.	Type
	type of mounting	output	Liectificat confiection	[m]	rait No.	туре
N/O contact						
	Insertable in the slot from above,	PNP	Cable, 3-wire	2.5	574335	SMT-8M-A-PS-24V-E-2,5-0E
	flush with the cylinder profile,					
	short design					
N/C contact						
./	Insertable in the slot from above,	PNP	Cable, 3-wire	7.5	574340	SMT-8M-A-PO-24V-E-7,5-OE
	flush with the cylinder profile,					
<u>~~~~</u>	short design					
Ordering data	a – Connecting cables					Technical data → Internet: neb
e.eeima autt	Electrical connection, left	Electrical co	nnection, right	Cable length	Part No.	Type
				[m]		.7
	Straight socket, M8x1, 3-pin	Cable, open	end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
				5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open	end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
S&				5	541341	NEBU-M8W3-K-5-LE3



Linear drives DGPIL FESTO

Accessories

Adapter kit Material:

HMVK Wrought aluminium alloy

Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/drive combinations	s with adapter kit			D	Oownload CAD data → www.festo.com
Combination	1 Drive	2 Drive	Adapter kit		
	Size	Size	CRC ¹⁾	Part No.	Туре
DGP(I)L, DGE, DGEA/DGPIL	DG	DGPIL	HMVK		
	Direct slide/slide mo	unting			
	18 ²⁾ , 25, 32 ³⁾	40	2	196781	HMVK-DL32/40-DLA18-32
	25 ²⁾ , 40	63	2 19678	196783	HMVK-DL63-DLA25/40
	Direct slide/profile m	ounting	<u> </u>		
	18	18	2	196780	HMVK-DL18/25-DL-18/25
	32 ³⁾ , 40	40	2	196781	HMVK-DL32/40-DLA18-32
2					

¹⁾ CRC2: Corrosion resistance class to Festo standard 940 070

Components with medium corrosion exposure. Externally visible components with significant decorative function in direct contact with normal industrial atmosphere or media such as coolants and lubricants.

2) Only for DGEA....

Only for DGPL/DGPIL-...